

## Flexion<sup>™</sup> N2

## Space-saving 6-Axis Robot with Revolutionary Design

- Compact Folding Arm Technology World's First\*
- Maximizes Motion Efficiency for Faster Cycle Times\*
- Unique Tight-space Motion Capability Keeps Arm Extremities Out of the Way\*
- 450 mm Reach and 2.5 kg Maximum Payload



## **Specifications**

		N2-A450	
Mounting type		Tabletop <sup>1</sup>	Ceiling
Degree of freedom		6	
Max. motion range	P point:	450 mm	
	through the center		
	of J4/J5/J6		
Wrist flange surface		532.2 mm	
Max. operating speed	Joint #1	297 °/s	
	Joint #2	297 °/s	
	Joint #3	356°/s	
	Joint #4	356°/s	
	Joint #5	360°/s	
	Joint #6	360°/s	
Weight (cable not included)		19 kg	
Repeatability	Joint #1-#6	±0.02 mm	
Max. motion range	Joint #1	±180°	
	Joint #2	±180°	
	Joint #3	±180°	
	Joint #4	±195°	
	Joint #5	±130	
	Joint #6	±360°	
Payload <sup>2</sup>	Rated	1 kg	
	Maximum	2.5 kg	
Allowable moment of inertia <sup>3</sup>	Joint #4	0.2 kg•m2	
	Joint #5	0.2 kg•m2	
	Joint #6	0.08 kg•m2	
Motor power consumption	Joint #1	100 W	
	Joint #2	100 W	
	Joint #3	100 W	
	Joint #4	30 W	
	Joint #5	30	
	Joint #6	15 W	
Installed wire for customer use		15 wires (D-sub) 8 pin (RJ45) Cat 5e or equivalent (2 cables)	
Installed pneumatic tube for customer use		Φ6 mm pneumatic tubes (2 tubes),	
Landa Hadisən amadan manada		Allowable pressure: 0.59 Mpa (6 kgf/cm²) (89 psi)	
Installation environment		Standard	
Available controllers		RC700A	
Safety standards		CE, ANSI/RIA15.06-2012	

Sales inquires: 562-290-5997 epsonrobots.com

<sup>\*</sup>Features exclusive to Epson's N-Series technology

<sup>1</sup> Manipulators are set to "Ceiling mounting" at shipment. To use the manipulators as "Tabletop mounting", you need to change the model settings. I 2 Do not exceed the maximum payload. I 3 If the center of gravity is at the center of each arm, set the eccentric quantity using INERTIA command.